

**International Journal of Current
Microbiology and Applied Sciences
(IJCMAS) NAAS RATING-5.38, ICV-95.39**
ISSN: 2319-7692 (Print) ISSN 2319-7706 (Online)

An International, Monthly, Online, Free Access, Peer Reviewed,
Indexed, fast track Scientific Research Journal

Certificate of Publication

This is to certify that the following article reviewed by editorial board and published in International Journal of Current Microbiology and Applied Sciences (IJCMAS) ISSN: 2319-7692 (Print) ISSN 2319-7706 (Online).

Int.J.Curr.Microbiol.App.Sci.2020.9.(11):2240-2246

<https://doi.org/10.20546/ijcmas.2020.911.269>

Design Concepts for the Development of a Semi-autonomous Robotic Platform for Environment Friendly Agriculture

P. Athira^{1*}, P. S. James², J. J. L. Bovas³ and D. S. Khatawkar¹

¹Department of Farm Machinery and Power Engineering, Kerala Agricultural University, Tavanur, Malappuram, Kerala, India

²Agricultural Research Station, Kerala Agricultural University, Mannuthy, Thrissur, Kerala, India

³Department of Agricultural Engineering, Gandhigram Rural Institute University, Dindigul, Tamilnadu, India

Dr. M. Prakash
Editor-in-chief

International Journal of Current Microbiology and Applied Sciences

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